

```

// Common U2F HID transport header - Proposed Standard
// 2014-10-09
// Editor: Jakob Ehrensvard, Yubico, jakob@yubico.com

#ifndef __U2FHID_H_INCLUDED__
#define __U2FHID_H_INCLUDED__

#ifdef _MSC_VER // Windows
typedef unsigned char     uint8_t;
typedef unsigned short    uint16_t;
typedef unsigned int      uint32_t;
typedef unsigned long int uint64_t;
#else
#include <stdint.h>
#endif

#ifdef __cplusplus
extern "C" {
#endif

// Size of HID reports

#define HID_RPT_SIZE          64      // Default size of raw HID report

// Frame layout - command- and continuation frames

#define CID_BROADCAST          0xffffffff // Broadcast channel id

#define TYPE_MASK               0x80      // Frame type mask
#define TYPE_INIT                0x80      // Initial frame identifier
#define TYPE_CONT                0x00      // Continuation frame identifier

typedef struct {
    uint32_t cid;                      // Channel identifier
    union {
        uint8_t type;                  // Frame type - b7 defines type
        struct {
            uint8_t cmd;              // Command - b7 set
            uint8_t bcnth;             // Message byte count - high part
            uint8_t bcntl;             // Message byte count - low part
            uint8_t data[HID_RPT_SIZE - 7]; // Data payload
        } init;
        struct {
            uint8_t seq;              // Sequence number - b7 cleared
            uint8_t data[HID_RPT_SIZE - 5]; // Data payload
        } cont;
    };
} U2FHID_FRAME;

#define FRAME_TYPE(f) ((f).type & TYPE_MASK)
#define FRAME_CMD(f)  ((f).init.cmd & ~TYPE_MASK)
#define MSG_LEN(f)    ((f).init.bcnth*256 + (f).init.bcctl)
#define FRAME_SEQ(f)  ((f).cont.seq & ~TYPE_MASK)

// HID usage- and usage-page definitions

#define FIDO_USAGE_PAGE        0xf1d0 // FIDO alliance HID usage page
#define FIDO_USAGE_U2FHID       0x01   // U2FHID usage for top-level collection
#define FIDO_USAGE_DATA_IN      0x20   // Raw IN data report
#define FIDO_USAGE_DATA_OUT     0x21   // Raw OUT data report

```

```

// General constants

#define U2FHID_IF_VERSION      2          // Current interface implementation version
#define U2FHID_TRANS_TIMEOUT    3000       // Default message timeout in ms

// U2FHID native commands

#define U2FHID_PING             (TYPE_INIT | 0x01) // Echo data through local processor
only
#define U2FHID_MSG               (TYPE_INIT | 0x03) // Send U2F message frame
#define U2FHID_LOCK              (TYPE_INIT | 0x04) // Send lock channel command
#define U2FHID_INIT              (TYPE_INIT | 0x06) // Channel initialization
#define U2FHID_WINK              (TYPE_INIT | 0x08) // Send device identification wink
#define U2FHID_SYNC              (TYPE_INIT | 0x3c) // Protocol resync command
#define U2FHID_ERROR             (TYPE_INIT | 0x3f) // Error response

#define U2FHID_VENDOR_FIRST     (TYPE_INIT | 0x40) // First vendor defined command
#define U2FHID_VENDOR_LAST      (TYPE_INIT | 0x7f) // Last vendor defined command

// U2FHID_INIT command defines

#define INIT_NONCE_SIZE          8          // Size of channel initialization challenge
#define CAPFLAG_WINK             0x01       // Device supports WINK command

typedef struct {
    uint8_t nonce[INIT_NONCE_SIZE];           // Client application nonce
} U2FHID_INIT_REQ;

typedef struct {
    uint8_t nonce[INIT_NONCE_SIZE];           // Client application nonce
    uint32_t cid;                            // Channel identifier
    uint8_t versionInterface;                // Interface version
    uint8_t versionMajor;                   // Major version number
    uint8_t versionMinor;                   // Minor version number
    uint8_t versionBuild;                  // Build version number
    uint8_t capFlags;                      // Capabilities flags
} U2FHID_INIT_RESP;

// U2FHID_SYNC command defines

typedef struct {
    uint8_t nonce;                          // Client application nonce
} U2FHID_SYNC_REQ;

typedef struct {
    uint8_t nonce;                          // Client application nonce
} U2FHID_SYNC_RESP;

// Low-level error codes. Return as negatives.

#define ERR_NONE                 0x00       // No error
#define ERR_INVALID_CMD          0x01       // Invalid command
#define ERR_INVALID_PAR          0x02       // Invalid parameter
#define ERR_INVALID_LEN          0x03       // Invalid message length
#define ERR_INVALID_SEQ          0x04       // Invalid message sequencing
#define ERR_MSG_TIMEOUT          0x05       // Message has timed out
#define ERR_CHANNEL_BUSY         0x06       // Channel busy
#define ERR_LOCK_REQUIRED        0x0a       // Command requires channel lock
#define ERR_SYNC_FAIL            0x0b       // SYNC command failed
#define ERR_OTHER                0x7f       // Other unspecified error

```

```
#ifdef __cplusplus
}
#endif
#endif // __U2FHID_H_INCLUEDED__
```